Recent Performance Improvements in the Community Atmospheric Model (CAM2) P. H. Worley, F. M. Hoffman, M. Vertenstein*, and J. B. Drake Oak Ridge National Laboratory and *National Center for Atmospheric Research

Introduction

One of the goals of the SciDAC project "Collaborative Design and Development of the Community Climate System Model for Terascale Computers" is to improve the performance portability of the Community Atmospheric Model (CAM2) and the Community Land Model (CLM2). Such impl take two forms: 1) modifications that improve performance in all configurations on all platforms, and 2) compile- or run-time options that can be used to improve performance for a specific platform processor count, or problem size. Since the inception of the project 18 months ago, significan progress has been made in both areas. Described here are performance impacts of impro to the physical parameterizations and the spectral Eulerian dynamical core as well as the ntation of a new interface between CAM2 and CLM2. Performance results are shown for the IBM p690 cluster at Oak Ridge National Laboratory and the HP AlphaServer SC ES45 cluster a Pittsburgh Supercomputer Center.

Physical Parameterization Optimizations

- Just prior to the SciDAC project, CAM developers chose to separate the data structures and parallel algorithms of the physical parameterizations (physics) from the dynamical core (dycore) to • support multiple dycores (spectral Eulerian, spectral semi-
- Lagrangian, and finite volume semi–Lagrangian) and
- allow physics and dynamics parallel algorithms to be optimized separately
- The SciDAC project introduced a new computational unit for the physics called the "chunk" -- an arbitrary subset of vertical columns distributed among MPI processes.
- Two tuning parameters: number of columns assigned to a chunk and number of chunks assigned to MPI processes.
- Each MPI process is assigned at least one chunk, and OpenMP parallelism is exploited when more than one chunk is assigned to an MPI process.



- Two decomposition strategies:
- 1. Use the same parallel decomposition as in the dycore, avoiding interprocess communication between the physics and dycore. The chunks are defined to balance the work associated with each chunk for a given process, thus load balancing any **OpenMP parallelism within an MPI process.**
- 2. Assign columns to chunks to balance the load across all chunks, and assign the same number of chunks to each processor. Chunk assignment also attempts to minimize the interprocessor communication in the physics/dycore interface.
- The chunk size (i.e., number of columns per chunk) determines memory access patterns, and can be tuned to the cache size or vector length of the computer architecture.



mance of CAM on a 128x64 horizontal grid with 26 vertical levels (T42L26) using 32 MF processes on a 32-way IBM p690 node (left) and on an HP AlphaServer SC (eight 4-way ES45 nodes) (right) is plotted as a function of the number of columns per chunk. Results are given for both globally load balanced chunks (option 1 above) and locally load balanced chunks (option 2 above). The locally load balanced 128-column chunks are equivalent to the latitude-slice decomposition formerly used in CAM. Neither small nor large chunks are optimal, and global load balancing improves performance. In addition, performance variation due to chunk size is identical to that of just the physics and the land model. (The land timings can not be separated from the physics timings due to load imbalances.)



spent moving data between the physics and the dycore, which includes any necessary interprocessor communication (bottom curves), for each of 32 MPI processes on the IBM p690 (left) and the HP AlphaServer SC (right). Time spent in bc_physics is 90% of the time spent in physics and represents all of the physics load imbalance. While the global load balancing algorithm is not perfect it decreases the range of variability by more than a factor of four in these experiments. The additional time spent moving data when using the global load balancing algorithm (bottom curves) is measurable, but the improvement due to global load balancing greatly outweighs this cost. This difference is a function of interprocessor communication performance, and a different result may hold on another architecture or for a different processor count or problem size.

Scaling Physics to Many Processors

the dycore, but use additional processors in the physics via OpenMP parallelism



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